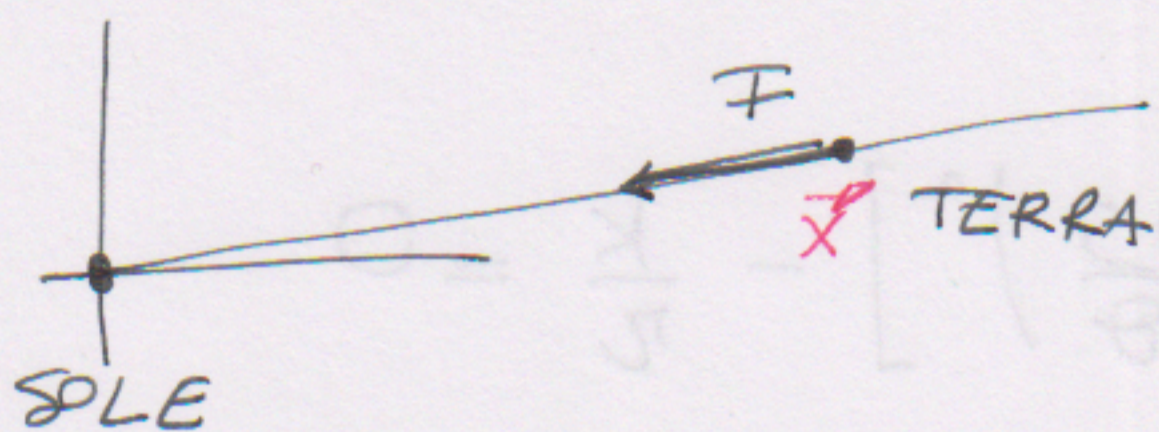


## Applicazione th H-J al problema di Keplero

Due corpi si attraggono con una forza che è inversamente prop. al quad. delle loro distanze ed è diretta come la congiungente fra i corpi



$$F = - \frac{\hat{x}}{|x|^3} K = - \frac{\hat{x}}{|x|^2} K$$

$$\hat{x} = \frac{x}{|x|}$$

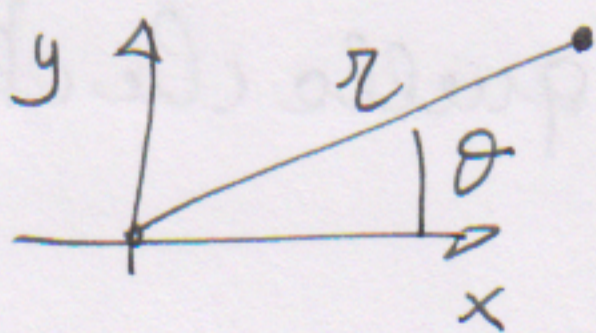
La forza  $F$  è conservativa  $F = -\nabla U$  con  $U = -\frac{K}{|x|}$

Verifichiamo  $-\nabla \cdot U = -\sum_i \vec{e}_i \frac{\partial U}{\partial x_i} =$

$$= +K \sum_i \vec{e}_i \frac{\partial}{\partial x_i} \frac{1}{\sqrt{\sum_j x_j^2}} = -K \sum_i \frac{\vec{e}_i x_i}{(\sum_j x_j^2)^{3/2}} = -K \frac{\vec{x}}{|x|^3}$$

$$\vec{x} = \sum_i \vec{e}_i x_i$$

Determiniamo il moto del corpo in coordinate polari piane



$$U = -\frac{K}{r}$$

$$H = T + U = \frac{1}{2m} \left( P_r^2 + \frac{P_\theta^2}{r^2} \right) - \frac{K}{r}$$

Notiamo subito che  $\theta$  è var. ciclica  $\Rightarrow P_\theta = \text{cost.}$



Dalle relazioni costitutive  $p_i = \frac{\partial S}{\partial q_i}$

$$p_r = \frac{\partial S}{\partial r} \quad p_\theta = \frac{\partial S}{\partial \theta}$$

Eq. H-J

$$\frac{\partial S}{\partial t} + \frac{1}{2m} \left[ \left( \frac{\partial S}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial S}{\partial \theta} \right)^2 \right] - \frac{K}{r} = 0$$

Tecnica di separazione delle variabili:

$$S = S_1(r) + S_2(\theta) + S_3(t)$$

$$+ \frac{1}{2m} \left[ \left( \frac{dS_1}{dr} \right)^2 + \frac{1}{r^2} \left( \frac{dS_2}{d\theta} \right)^2 \right] - \frac{K}{r} = - \frac{dS_3}{dt}$$

" costante

$$- \frac{dS_3}{dt} = E \text{ cost.} = S_3 = -Et$$

$$\frac{1}{2m} \left( \frac{dS_1}{dr} \right)^2 + \frac{1}{2m r^2} \left( \frac{dS_2}{d\theta} \right)^2 - \frac{K}{r} = E$$

Tratto la cost. che dip. da  $\theta$  dalla da quella che dip. da  $E$

$$\left( \frac{dS_2}{d\theta} \right)^2 = r^2 \left[ E \cdot 2m + \frac{K \cdot 2m}{r} - \left( \frac{dS_1}{dr} \right)^2 \right]$$

$$f(\theta) = g(r)$$



come prima  $\left(\frac{dS_2}{d\theta}\right)^2 = \beta^2 = \text{cost.} \Rightarrow S_2 = \beta\theta$

$$\beta^2 = r^2 \left[ 2mE + \frac{2Km}{r} - \left(\frac{dS_1}{dr}\right)^2 \right]$$

• Esplicito  $\frac{dS_1}{dr}$

$$\frac{dS_1}{dr} = \sqrt{-\frac{\beta^2}{r^2} + 2mE + \frac{2Km}{r}}$$

$$S_1 = \int^r \sqrt{2mE + \frac{2Km}{r} - \frac{\beta^2}{r^2}} dr$$

Funzione H-J

$$S = \int^r \sqrt{2mE + \frac{2Km}{r} - \frac{\beta^2}{r^2}} - Et + \beta\theta$$

Quindi sapendo che i momenti coniugati  $P_r$  e  $P_\theta$  sono costanti, posso scegliere  $P_\theta = \beta$   $P_r = E$

Formula costitutiva

$$Q_i = \frac{\partial S}{\partial P_i} \Rightarrow Q_r = \frac{\partial S}{\partial P_r} \quad Q_\theta = \frac{\partial S}{\partial P_\theta}$$

$$Q_r = \frac{\partial S}{\partial E} = \frac{\partial}{\partial E} \int^r \sqrt{2mE + \frac{2Km}{r} - \frac{\beta^2}{r^2}} - t$$

$$Q_\theta = \frac{\partial S}{\partial \beta} = \frac{\partial}{\partial \beta} \int^r \sqrt{2mE + \frac{2Km}{r} - \frac{\beta^2}{r^2}} + \theta$$



$$Q\theta = \theta + \frac{\partial}{\partial \beta} \int \sqrt{2mE + 2\frac{Km}{z} - \frac{\beta^2}{z^2}} dz$$

$$= \theta + \int \frac{(-)\beta}{z^2 \sqrt{2mE + 2\frac{Km}{z} - \frac{\beta^2}{z^2}}} dz = \theta + \int \frac{1}{\sqrt{2mE + 2\frac{Km}{z} - \frac{\beta^2}{z^2}}} dz \quad z = 1/w$$

L'integrale è della forma  $\left. \begin{aligned} &= \theta + \frac{1}{\beta} \int \frac{1}{\sqrt{\frac{2mE}{\beta^2} + \frac{2Km}{\beta^2} w - \beta^2 w^2}} dw \end{aligned} \right\}$

$$\int \frac{1}{\sqrt{ax^2+bx+c}} dx \Rightarrow a < 0 \quad 4ac - b^2 < 0$$

$$= -\frac{1}{\sqrt{-a}} \arcsin \left( \frac{2ax+b}{\sqrt{b^2-4ac}} \right)$$

$$Q\theta = \theta + \arcsin \left( \frac{-2w + \frac{2Km}{\beta^2}}{\sqrt{\frac{4K^2m^4}{\beta^4} + 4 \cdot \frac{2mE}{\beta^2}}} \right) =$$

$$= \theta + \arcsin \left( \frac{-\frac{2Km}{\beta^2} + 2w}{\sqrt{\frac{4K^2m^4}{\beta^4} \left( 1 + \frac{2E\beta^2}{2mK^2} \right)}} \right) =$$

$$= \theta + \arcsin \left( \frac{-1 + w \frac{\beta^2}{Km}}{\sqrt{1 + \frac{2E\beta^2}{mK^2}}} \right)$$



Sostituiremo  $r = 1/u$  e mettiamo la formula. Dopo un po' di calcoli si ottiene

$$r = \frac{\beta^2}{mk} \frac{1}{\left| 1 + \sqrt{1 + \frac{2E\beta^2}{mk^2}} \cdot \cos\left(\theta - \alpha_0 + \frac{\pi}{2}\right) \right|}$$

↓  
costante!

Descrive la traiettoria nel piano:  $r = r(\theta)$   
la distanza dall'origine è espressa in funzione dell'angolo

Mettiamo nella forma

$$r = \frac{p}{1 + \varepsilon \cos \varphi}$$

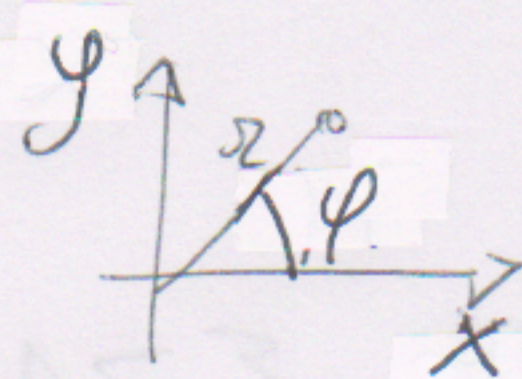
con  $p = \frac{\beta^2}{mk}$

$\varphi = \theta - \alpha_0 + \frac{\pi}{2}$   
costante

$$\varepsilon = \sqrt{1 + \frac{2E\beta^2}{k^2 m}} \rightarrow \text{costante}$$

$$r + \varepsilon r \cos \varphi = p$$

$$r \cos \varphi = x$$



~~Equation~~  $\rightarrow$  ~~Equation~~

~~Equation~~

$$r = p - \varepsilon x \Rightarrow r^2 = p^2 + \varepsilon^2 x^2 - 2\varepsilon p x$$

$$x^2 + y^2 = p^2 + \varepsilon^2 x^2 - 2\varepsilon p x$$



$$x^2(1-\varepsilon^2) + y^2 + 2\varepsilon px = p^2 \Rightarrow \text{travettoria}$$

del pt in coord.  
cartesiane

$$\text{caso } \varepsilon = 1$$

$$y^2 + 2px = p^2 \Rightarrow x = \frac{p^2 - y^2}{2p} \Rightarrow \text{PARABOLA}$$

$$\text{caso } \varepsilon < 1; \text{ poniamo } x' = x + \frac{\varepsilon p}{1-\varepsilon^2} \quad \text{Trasl. orig.}$$

$$x = x' - \frac{\varepsilon p}{1-\varepsilon^2}$$

$$\cancel{x'^2(1-\varepsilon^2)} - \cancel{2x'\varepsilon p} + \frac{\varepsilon^2 p^2}{1-\varepsilon^2} + y^2 + \cancel{2\varepsilon p x'} + \frac{2\varepsilon p^2 p}{1-\varepsilon^2} = p^2$$

$$\overbrace{(x')^2(1-\varepsilon^2)}^{>0} + y^2 = p^2 + \frac{\varepsilon^2 p^2}{1-\varepsilon^2} = k \Rightarrow \text{ELLISSE}$$

caso  $\varepsilon > 1$  l'eq. precedente ha la forma

$$-(x')^2 \alpha + y^2 = k \Rightarrow \text{IPERBOLE}$$

$$\downarrow \\ \alpha > 0$$



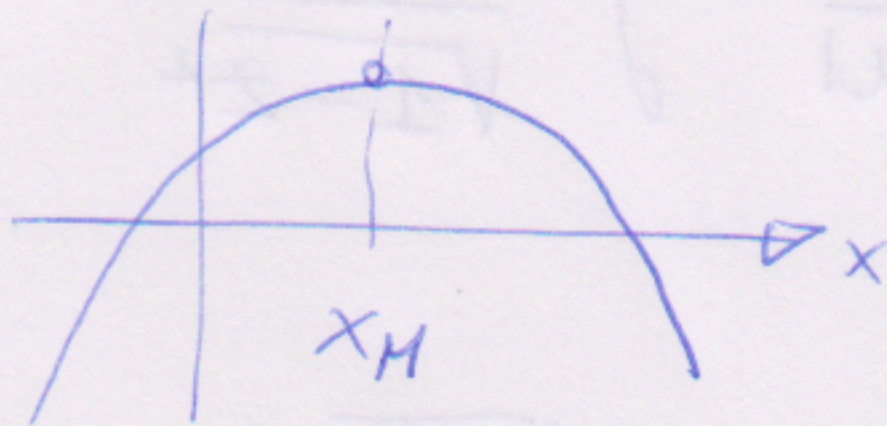
calcoliamo

$$\int \frac{1}{\sqrt{ax^2+bx+c}} dx$$

Cerchiamo una traduzione che elimini il termine lineare

$$ax^2+bx+c \quad a < 0$$

$$b^2-4ac > 0$$



cerco il max

$$\frac{d}{dx} (ax^2+bx+c) = 2ax+b=0 \Rightarrow x_M = -\frac{b}{2a}$$

Poniamo  $y = x - x_M = x + \frac{b}{2a}$        $x = y - \frac{b}{2a}$

$$ax^2+bx+c = a \left| y - \frac{b}{2a} \right|^2 + b \left| y - \frac{b}{2a} \right| + c =$$

$$= a \left( y^2 + \frac{b^2}{4a^2} - \frac{by}{a} \right) + by - \frac{b^2}{2a} + c =$$

$$= ay^2 - \frac{b^2}{4a} + c = ay^2 + c' \quad \text{con } c' = c - \frac{b^2}{4a}$$

NOTA  $c' = \frac{4ac-b^2}{4a} < 0 > 0$

$$\int \frac{1}{\sqrt{ax^2+bx+c}} dx = \int \frac{1}{\sqrt{ay^2+c'}} dy \quad y = x + \frac{b}{2a}$$



$$z = -|a|$$

$$= \frac{1}{\sqrt{c}}$$

$$\int \frac{1}{\sqrt{1 - \frac{|a|}{c} y^2}} dx$$

$$z = y \sqrt{\frac{|a|}{c}}$$

$$dy = dz \sqrt{\frac{c}{|a|}}$$

$$= \frac{1}{\sqrt{|a|}} \int \frac{1}{\sqrt{1 - z^2}} dz = \frac{1}{\sqrt{|a|}} \arcsin \left( \frac{x + \frac{b}{2a}}{\sqrt{\frac{|a|}{c}}} \right)$$

$$\text{Risultato} \quad \sqrt{\frac{|a|}{c}} \left( x + \frac{b}{2a} \right) = \sqrt{\frac{|a|}{c}} \left( \frac{2ax + b}{2a} \right)$$

$$= \sqrt{\frac{|a|}{c}} \left( -\frac{(2ax + b)}{2|a|} \right) = \frac{-(2ax + b)}{\sqrt{|a| \cdot 4c}}$$

$$= \frac{-(2ax + b)}{\sqrt{4|a|c - \frac{b^2 |a|}{a}}} = \frac{-(2ax + b)}{\sqrt{b^2 - 4ac}}$$

$$\text{Ottengo} \quad \int \frac{1}{\sqrt{ax^2 + bx + c}} dx = -\frac{1}{\sqrt{|a|}} \arcsin \left( \frac{2ax + b}{\sqrt{b^2 - 4ac}} \right)$$