For a system of two particles 1 and 2 with coordinates (x_1, y_1, z_1) and (x_2, y_2, z_2) the potential energy of interaction between the particles is usually a function of only the relative coordinates x_2-x_1 , y_2-y_1 and z_2-z_1 of the particles. In this case the two-particle problem can be simplified to two separate one-particle problems

The Hamiltonian is $\widehat{H} = \widehat{T} + \widehat{V}$

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Kinetic energy operator

$$\widehat{T} = -\frac{\hbar^2}{2m_1} \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial y_1^2} + \frac{\partial^2}{\partial z_1^2} \right) - \frac{\hbar^2}{2m_2} \left(\frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial y_2^2} + \frac{\partial^2}{\partial z_2^2} \right)$$

The Hamiltonian is
$$\widehat{H} = \widehat{T} + \widehat{V}$$

1) Potential energy operator for 2 charged particles (e.g. proton + electron, anion + cation)

$$V(x_1,y_1,z_1,x_2,y_2,z_2) = \frac{1}{4\pi\varepsilon_0} \frac{q_1q_2}{\sqrt{(x_2-x_1)^2+(y_2-y_1)^2+(z_2-z_1)^2}}$$

2) Potential energy operator for a 3D harmonic oscillator

$$V(x_1, y_1, z_1, x_2, y_2, z_2) = \frac{1}{2}k\left(\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} - r_0\right)^2$$

3) Potential energy operator for a 3D rigid rotor

$$V(x_1, y_1, z_1, x_2, y_2, z_2) = 0$$
 (or in general $V = constant$)

We make a change of coordinates

$$\mathbf{r} = \mathbf{r}_2 - \mathbf{r}_1$$

$$\mathbf{r} = \mathbf{r}_2 - \mathbf{r}_1 \qquad \mathbf{R} = \frac{m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2}{M}$$

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

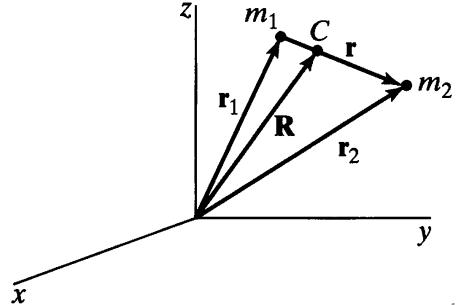
$$\mathbf{R} = X\mathbf{i} + Y\mathbf{j} + Z\mathbf{k}$$

where

$$\mathbf{r}_1 = x_1 \mathbf{i} + y_1 \mathbf{j} + z_1 \mathbf{k}$$

$$\mathbf{r}_2 = x_2 \mathbf{i} + y_2 \mathbf{j} + z_2 \mathbf{k}$$

$$M = m_1 + m_2$$



$$\mathbf{r} = \mathbf{r}_2 - \mathbf{r}_1 \qquad \mathbf{R} = \frac{m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2}{M}$$

These equations represent a transformation of coordinates

from
$$x_1$$
 y_1 z_1 x_2 y_2 z_2 to X Y Z x y z

The relations between the
$$x=x_2-x_1$$
 $X=(m_1x_1+m_2x_2)/M$ $Y=y_2-y_1$ $Y=(m_1y_1+m_2y_2)/M$ coordinates are $z=z_2-z_1$ $Z=(m_1z_1+m_2z_2)/M$

We will consider what happens to the Hamiltonian under this transformation of coordinates

The potential energy is simply a function of **r**

$$V(x_1, y_1, z_1, x_2, y_2, z_2) = V(x, y, z)$$

For example, considering the electric potential energy, we have

$$V(x_1, y_1, z_1, x_2, y_2, z_2) = \frac{1}{4\pi\varepsilon_0} \frac{q_1q_2}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}}$$

It can be easily written as a function of the new coordinates

$$V(x, y, z) = \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{\sqrt{x^2 + y^2 + z^2}}$$

We have seen that the kinetic energy of the 2 particles is

$$\hat{T} = -\frac{\hbar^2}{2m_1} \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial y_1^2} + \frac{\partial^2}{\partial z_1^2} \right) - \frac{\hbar^2}{2m_2} \left(\frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial y_2^2} + \frac{\partial^2}{\partial z_2^2} \right)$$

We need to transform the above partial derivatives in the following ones

$$\frac{\partial^2}{\partial x^2} \quad \frac{\partial^2}{\partial y^2} \quad \frac{\partial^2}{\partial z^2} \quad \frac{\partial^2}{\partial X^2} \quad \frac{\partial^2}{\partial Y^2} \quad \frac{\partial^2}{\partial Z^2}$$

To this aim we exploit the <u>chain rules</u> For coordinates x_1 , y_1 and z_1 , the rules are the following

$$\frac{\partial}{\partial x_1} = \frac{\partial x}{\partial x_1} \frac{\partial}{\partial x} + \frac{\partial y}{\partial x_1} \frac{\partial}{\partial y} + \frac{\partial z}{\partial x_1} \frac{\partial}{\partial z} + \frac{\partial X}{\partial x_1} \frac{\partial}{\partial X} + \frac{\partial Y}{\partial x_1} \frac{\partial}{\partial Y} + \frac{\partial Z}{\partial x_1} \frac{\partial}{\partial Z}$$

$$\frac{\partial}{\partial y_1} = \frac{\partial x}{\partial y_1} \frac{\partial}{\partial x} + \frac{\partial y}{\partial y_1} \frac{\partial}{\partial y} + \frac{\partial z}{\partial y_1} \frac{\partial}{\partial z} + \frac{\partial X}{\partial y_1} \frac{\partial}{\partial X} + \frac{\partial Y}{\partial y_1} \frac{\partial}{\partial Y} + \frac{\partial Z}{\partial y_1} \frac{\partial}{\partial Z}$$

$$\frac{\partial}{\partial z_1} = \frac{\partial x}{\partial z_1} \frac{\partial}{\partial x} + \frac{\partial y}{\partial z_1} \frac{\partial}{\partial y} + \frac{\partial z}{\partial z_1} \frac{\partial}{\partial z} + \frac{\partial X}{\partial z_1} \frac{\partial}{\partial X} + \frac{\partial Y}{\partial z_1} \frac{\partial}{\partial Y} + \frac{\partial Z}{\partial z_1} \frac{\partial}{\partial Z}$$

Analogous expressions can be written for the derivatives involving x_2 , y_2 and z_2

After some algebra, we get

$$\frac{\partial}{\partial x_1} = -\frac{\partial}{\partial x} + \frac{m_1}{M} \frac{\partial}{\partial X}$$

$$\frac{\partial}{\partial y_1} = -\frac{\partial}{\partial y} + \frac{m_1}{M} \frac{\partial}{\partial Y}$$

$$\frac{\partial}{\partial z_1} = -\frac{\partial}{\partial z} + \frac{m_1}{M} \frac{\partial}{\partial Z}$$

$$\frac{\partial}{\partial x_2} = \frac{\partial}{\partial x} + \frac{m_2}{M} \frac{\partial}{\partial X}$$

$$\frac{\partial}{\partial y_2} = \frac{\partial}{\partial y} + \frac{m_2}{M} \frac{\partial}{\partial Y}$$

$$\frac{\partial}{\partial z_2} = \frac{\partial}{\partial z} + \frac{m_2}{M} \frac{\partial}{\partial z}$$

Using the previous operators in the following kinetic energy operator

$$\widehat{T} = -\frac{\hbar^2}{2m_1} \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial y_1^2} + \frac{\partial^2}{\partial z_1^2} \right) - \frac{\hbar^2}{2m_2} \left(\frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial y_2^2} + \frac{\partial^2}{\partial z_2^2} \right)$$

we obtain
$$\nabla^2_{\mu} = -\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) - \frac{\hbar^2}{2M} \left(\frac{\partial^2}{\partial X^2} + \frac{\partial^2}{\partial Y^2} + \frac{\partial^2}{\partial Z^2} \right)$$

$$\widehat{T}=-rac{\hbar^2}{2\mu}
abla_{\mu}^2-rac{\hbar^2}{2M}
abla_{M}^2$$
 where $\mu=rac{m_1m_2}{M}$ Reduced Mass

$$\widehat{T} = -\frac{\hbar^2}{2M} \nabla_M^2 - \frac{\hbar^2}{2\mu} \nabla_\mu^2$$

The first term can be viewed as the kinetic energy of a hypothetical particle of mass M moving with the coordinates of the center of mass (**translational motion**)

The second term can be viewed as the kinetic energy of internal (relative) motion of the 2 particles. This internal motion can be of two types. The distance r between the two particles can change (**vibration**), and the direction of the r vector can change (**rotation**)

With the new definitions of \widehat{V} and \widehat{T} , the Hamiltonian operator becomes as follows

$$\widehat{H} = -\frac{\hbar^2}{2M} \nabla_M^2 - \frac{\hbar^2}{2\mu} \nabla_\mu^2 + \widehat{V}(x, y, z)$$

The Hamiltonian can be viewed as the sum of the Hamiltonians of two hypothetical noninteracting particles with masses M and μ , the latter being subject to the potential-energy function V(x,y,z). We can apply the results obtained for two noninteracting particles

Memo
$$\widehat{H} = -\frac{\hbar^2}{2M} \nabla_M^2 - \frac{\hbar^2}{2\mu} \nabla_\mu^2 + \widehat{V}(x, y, z)$$

Total energy
$$E=E_M+E_\mu$$

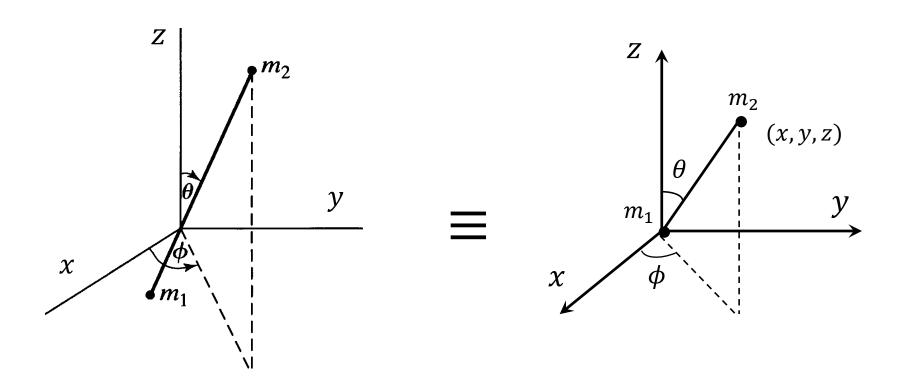
$$\psi = \psi_M \, \psi_\mu$$

where
$$\begin{cases} -\frac{\hbar^2}{2M}\nabla_M^2\psi_M=E_M\psi_M\\ -\frac{\hbar^2}{2\mu}\nabla_\mu^2\psi_\mu+V(x,y,z)\psi_\mu=E_\mu\psi_\mu \end{cases}$$

By **two-particle rigid rotor** we mean a two-particle system with the particles held at a fixed distance d from each other. The kinetic energy of internal motion is wholly rotational energy. The energy of the rotor is wholly kinetic, and V(x, y, z) = 0. The Schrödinger equation for the internal motion is

$$-\frac{\hbar^2}{2\mu}\nabla^2_{\mu}\psi_{\mu} = E_{\mu}\psi_{\mu}$$

Instead of the relative Cartesian coordinates x, y, z, it will prove more fruitful to use the relative spherical coordinates r, θ , ϕ



Coordinate system for the two-particle rigid rotor

In Cartesian coordinates the Schrödinger equation is

$$-\frac{\hbar^2}{2\mu}\nabla^2_{\mu}\psi(x,y,z) = E \psi(x,y,z)$$

To go from Cartesian to spherical coordinates, we exploit the results obtained from angular momentum. In particular, we use the chain rule

To perform the transformation to polar spherical coordinates, we use the chain rule

$$\frac{\partial}{\partial x} = \left(\frac{\partial r}{\partial x}\right)_{y,z} \frac{\partial}{\partial r} + \left(\frac{\partial \theta}{\partial x}\right)_{y,z} \frac{\partial}{\partial \theta} + \left(\frac{\partial \phi}{\partial x}\right)_{y,z} \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial y} = \left(\frac{\partial r}{\partial y}\right)_{x,z} \frac{\partial}{\partial r} + \left(\frac{\partial \theta}{\partial y}\right)_{x,z} \frac{\partial}{\partial \theta} + \left(\frac{\partial \phi}{\partial y}\right)_{x,z} \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial z} = \left(\frac{\partial r}{\partial z}\right)_{x,y} \frac{\partial}{\partial r} + \left(\frac{\partial \theta}{\partial z}\right)_{x,y} \frac{\partial}{\partial \theta} + \left(\frac{\partial \phi}{\partial z}\right)_{x,y} \frac{\partial}{\partial \phi}$$

Because the distance r is fixed (it does not depend on x, y, z). The distance r corresponds to the (fixed) bond length

After substitutions, we obtain

$$\frac{\partial}{\partial x} = \sin\theta \cos\phi \frac{\partial}{\partial r} + \frac{\cos\theta \cos\phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin\phi}{r \sin\theta} \frac{\partial}{\partial \phi}$$

Note that in these equations r is fixed

$$\frac{\partial}{\partial y} = \sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \theta \sin \phi}{r} \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial z} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}$$

We use the operators above to determine the kinetic energy operator

$$-\frac{\hbar^2}{2\mu}\nabla_{\mu}^2 = -\frac{\hbar^2}{2\mu}\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right)$$

After algebra steps, the Schrödinger equation becomes as follows

The variable r is the distance between the 2 atoms (bond length). It has been replaced by d to outline that it is fixed

$$-\frac{\hbar^2}{2 \mu d^2} \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right) \psi = E \psi$$

Recalling the definition of the square angular momentum operator

$$\hat{L}^2 = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \, \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right)$$

we can write
$$\frac{1}{2 \mu d^2} \hat{L}^2 \psi = E \psi$$

Memo

$$\frac{1}{2 \mu d^2} \hat{L}^2 \psi = E \psi$$

We can rearrange as

$$\hat{L}^2 \psi = 2 \,\mu \, d^2 E \,\psi$$

But, from the angular momentum solution, we know that

$$\hat{L}^2 Y_l^m(\theta, \phi) = l(l+1)\hbar^2 Y_l^m(\theta, \phi)$$

This implies that the wave-functions are the spherical harmonics

$$\psi(\theta,\phi) = Y_l^m(\theta,\phi)$$

While the **energy** is (we have replaced l with J)

$$E = \frac{J(J+1)\hbar^2}{2 \mu d^2} \qquad J = 0, 1, 2, \dots$$

The **moment of inertia** I of a system of n particles about some particular axis in space as defined as

$$I = \sum_{i=1}^{n} m_i r_i^2$$

where m_i is the mass of the ith atom and r_i is the perpendicular distance from this particle to the axis. The value of I depends on the choice of axis. For the two-particle rigid rotor, we choose our axis to be a line that passes through the center of mass and is perpendicular to the line joining m_1 and m_2

We assume to put the molecule along the x axis with the center of mass on the axis origin, we can write

$$X = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2} = 0 \qquad \Longrightarrow \qquad m_1 x_1 + m_2 x_2 = 0 \tag{1}$$

The bond length is $d = x_2 - x_1$ (2)

The moment of inertia is $I = m_1 x_1^2 + m_2 x_2^2$ (3)

Equations 1, 2 and 3 give $I = \mu d^2$

The energy of the two-particle rigid rotor is

$$E = \frac{J(J+1)\hbar^2}{2J} \qquad J = 0, 1, 2, \dots$$

The energy depends on J only, but the wave function depends on J and m. For each value of J, there are 2J+1 values of m, ranging from -J to J. Hence the energy levels are (2J+1)-fold degenerate

The rotational levels of a diatomic molecule in gas phase can be well approximated by the two-particle rigid-rotor energies

When a diatomic molecule absorbs or emits radiation the allowed pure-rotational transitions are

$$\Delta J = \pm 1$$

In addition, a molecule must have a nonzero dipole moment in order to show a pure-rotational spectrum. A pure-rotational transition is one where only the rotational quantum number changes. The pure-rotational spectrum falls in the microwave (or the far-infrared) region

$$\nu = \frac{E_{J+1} - E_J}{h} = 2(J+1)B$$
Rotational constant
$$B = \frac{h}{8\pi^2 I}$$

$$B = 0, 1, 2, ...$$

$$B = 0, 1, 2, ...$$

Rotational spectrum of a rigid rotor